# On n-Widths and Interpolation by Polynomial Splines 

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## 1. Introduction

We consider the following quasi-Hermite interpolation problem. Let $n, r$, $k, z_{j}, q_{0 i}\left(0 \leqslant i \leqslant z_{0}-1\right), q_{1 i}\left(0 \leqslant i \leqslant z_{k+1}-1\right)$ be given integers such that $n \geqslant 0, r \geqslant 2, k \geqslant 0,1 \leqslant z_{j} \leqslant r-1$ for $1 \leqslant j \leqslant k, 0 \leqslant z_{j} \leqslant r-1$ for $j=0$ and $j=k+1,0 \leqslant q_{0,0}<\cdots<q_{0, z_{0}-1} \leqslant r-2$, and $0 \leqslant$ $q_{1,0}<\cdots<q_{1, z_{k+1}-1} \leqslant r-2$. Let also $k+2$ abscissae $x_{j}$ be given such that

$$
0=x_{0}<x_{1}<\cdots<x_{k+1}=1
$$

Definition 1. We say that a function $g \in C^{r-2}[0,1]$ interpolates $f \in C^{r-2}[0,1]$, provided that

$$
\begin{array}{ll}
g^{(q)}\left(x_{j}\right)=f^{(q)}\left(x_{j}\right) & \text { for } 0 \leqslant q \leqslant z_{j}-1, \quad 1 \leqslant j \leqslant k \\
g^{\left(q_{0 i}\right)}(0)=f^{\left(q_{0 i}\right)}(0) & \text { for } \left.0 \leqslant i \leqslant z_{0}-1 \text { (no condition if } z_{0}=0\right), \quad(1  \tag{1}\\
g^{\left(q_{1 i}\right)}(1)=f^{\left(q_{1 i}\right)}(1) & \text { for } \left.0 \leqslant i \leqslant z_{k+1}-1 \text { (no condition if } z_{k+1}=0\right) .
\end{array}
$$

Throughout this paper we shall interpolate by polynomial splines.

## Definition 2. Let

$$
\begin{equation*}
\Delta: 0=t_{0}<t_{1}<\cdots<t_{n+1}=1 \tag{2}
\end{equation*}
$$

be a collection of knots. The set of polynomial splines of degree $r-1$ with knots $\Delta$ is

$$
\operatorname{Sp}(r, \Delta)=\left\{s \in C^{r-2}[0,1]: s(x)=\sum_{i=0}^{r-1} a_{i} x^{i}+\sum_{j=1}^{n} c_{j}\left(x-t_{j}\right)_{+}^{r-1}\right\},
$$

[^0]where $a_{i}$ and $c_{j}$ are any real numbers and $x_{+}^{r-1}=x^{r-1}$ if $x>0, x_{+}^{r-1}=0$ if $x \leqslant 0$.
We shall interpolate functions $f \in C^{r-2}[0,1]$ and, in particular, functions belonging to the following classes.

Definition 3. If $\Delta$ denotes a collection (2) of knots, then

$$
\begin{aligned}
W_{r, 4}= & \left\{f \in C^{r-2}[0,1]: f^{(r-1)}\right. \text { is absolutely continuous in } \\
& \text { each open interval } \left.\left(t_{j}, t_{j+1}\right), 0 \leqslant j \leqslant n\right\} .
\end{aligned}
$$

If $w \in L^{1}[0,1]$, then

$$
W_{r, w, \Delta}=\left\{f \in W_{r, \Delta}\left|f^{(r)}(x)\right| \leqslant|w(x)| \text { a.e. in }[0,1]\right\} .
$$

In particular

$$
W_{r, 1, \Delta}=\left\{f \in W_{r, \Delta}:\left|f^{(r)}(x)\right| \leqslant 1 \text { a.e. in }[0,1]\right\} .
$$

In Section 2 we discuss necessary and sufficient conditions under which the interpolation problem (1) has a unique spline interpolant $s_{f} \in \mathrm{Sp}(r, \Delta)$ for every function $f \in C^{r-2}[0,1]$.
If the interpolation problem (1) satisfies these conditions then Theorem 2 in Section 3 states that the classes $W_{r, w, \Delta}$ possess a unique extremal function $F \in W_{r, w, \Delta}$ provided that $w \in L^{1}[0,1]$ and $|w(x)|>0$ a.e. in [0, 1]. The functions $F$ are even locally extremal, i.e.

$$
\sup \left\{\left|f(x)-s_{f}(x)\right|: f \in W_{r, w, \Delta\}}=|F(x)| \quad \text { for every } \quad x \in[0,1] .\right.
$$

In Section 4 we study the classes of functions $W_{r}:=\left\{f \mid f^{(r-1)}\right.$ absolutely continuous on $[0,1],\left|f^{(r)}(x)\right| \leqslant 1$ a.e. on $\left.[0,1]\right\}$ and the splines $\operatorname{Sp}\left(r, \Delta^{*}\right)$ with equidistant knots $\Delta^{*}$. If we choose $x_{j}$ to be the knots $\Delta^{*}$ (if $r$ is even) and to be the midpoints between the knots $\Delta^{*}$ (if $r$ is odd) and choose suitable interpolation conditions at the endpoints $x_{0}=0$ and $x_{k+1}=1$, then Theorem 2 leads to the inequality

$$
\sup \left\{\left\|f-s_{f}\right\|_{|c| 0,10}: f \in W_{r}\right\} \leqslant d_{n}\left(W_{r}\right)
$$

where $d_{n}\left(W_{\tau}\right)$ denotes the $n$-width of $W_{r}$ in $C[0,1]$. Since $\operatorname{dim} \operatorname{Sp}\left(r, \Delta^{*}\right)=$ $n+r$ we have obtained the interesting result that the above described interpolation by polynomial splines $\operatorname{Sp}\left(r, \Delta^{*}\right)$ with equidistant knots leads to asymptotically best possible error bounds in the sense of $n$-widths.
In Section 5 the application of Theorem 2 to cubic splines with arbitrary knots $\Delta$ leads to some new local error bounds.

## 2. Existence and Uniqueness in Spline Interpolation

There is a series of papers on the existence and uniqueness in spline interpolation for more general interpolation problems than (1) (see Schoenberg [9], Karlin [4], Karlin and Karon [5], Melkman [6], a.o.). In particular, the following theorem is a special case of Melkman [6; Theorem 1].

Theorem 1. Let $\Delta$ be a collection (2) of $n$ knots in ( 0,1 ). Assume that the interpolation problem (1) contains $n+r$ conditions, i.e.

$$
\begin{equation*}
\sum_{j=0}^{k+1} z_{j}=n+r . \tag{3}
\end{equation*}
$$

Let $m_{q}(q=0,1, \ldots, r-2)$ denote the number of interpolation conditions (1) for the $q$-th derivative $f^{(9)}$ in $[0,1]$, and let $L_{j}$ and $U_{j}(j=1, \ldots, n)$ denote the number of interpolation conditions (1) in $\left[0, t_{j}\right)$ and $\left(t_{j}, 1\right]$, respectively. Then the spline interpolant $s_{f} \in \operatorname{Sp}(r, \Delta)$ exists and is unique for every function $f \in C^{r-2}[0,1]$ if and only if Polya's conditions

$$
\begin{equation*}
\sum_{q=0}^{p} m_{q} \geqslant p+1, \quad p=0,1, \ldots, r-2 \tag{4}
\end{equation*}
$$

and the inequalities

$$
\begin{equation*}
L_{j} \geqslant j, \quad U_{j} \geqslant n+1-j, \quad j=1, \ldots, n \tag{5}
\end{equation*}
$$

are satisfied.

## 3. Local Upper Bounds in Spline Interpolation

One of our main results is the following theorem. It provides best possible local upper bounds in polynomial spline interpolation for classes $W_{r, w, \Delta}$ of functions.

ThEOREM 2. Let a quasi-Hermite interpolation problem (1) and a collection (2) of knots $\Delta$ be given such that the assumptions (3)-(5) hold.
(a) For each function $w \in L^{1}[0,1]$ there exists a unique function $F \in W_{r, w, \Delta}$ with the properties
(i) F interpolates the zero function (see Definition 1).
(ii) $F^{(r)}(x)=(-1)^{j}|w(x)|$ a.e. in $\left(t_{j}, t_{j+1}\right), 0 \leqslant j \leqslant n$.
(b) If $|w(x)|>0$ a.e. on $[0,1]$, for each $f \in W_{r, w, \Delta}$ the unique spline interpolant $s_{f} \in \operatorname{Sp}(r, \Delta)$ satisfies the inequalities

$$
\begin{array}{cl}
\left|f(x)-s_{f}(x)\right| \leqslant|F(x)| & \text { for all } x \in[0,1] \\
\left|f^{\left(z_{j}\right)}\left(x_{j}\right)-s_{f}^{\left(z_{j}\right)}\left(x_{j}\right)\right| \leqslant\left|F^{\left(z_{j}\right)}\left(x_{j}\right)\right| & \text { for } 1 \leqslant j \leqslant k \text { if } z_{j} \leqslant r-2 \\
\left|f^{(q)}\left(x_{j}\right)-s_{f}^{(q)}\left(x_{j}\right)\right| \leqslant\left|F^{(o)}\left(x_{j}\right)\right| & \text { for } j=0, j=k+1 \text { and } \\
& \text { all } 0 \leqslant q \leqslant r-2 . \tag{9}
\end{array}
$$

Remark 1. Since $F$ has the spline interpolant $s_{F} \equiv 0$ it follows from (7) that

$$
\sup \left\{\left|f(x)-s_{f}(x)\right|: f \in W_{r, w, \Delta\}}=|F(x)| \quad \text { for each } \quad x \in[0,1],\right.
$$

which means that $F$ is extremal in $W_{r, w, \Delta}$ for each $x$.
Proof of Theorem 2. (a) Let $u \in L^{1}[0,1]$ be defined by $u(x)=(-1)^{j}|w(x)|$ for $x \in\left(t_{j}, t_{j+1}\right), 0 \leqslant j \leqslant n$. Let $G$ be any $r$-th integral of $u$ in $[0,1]$. Then $G \in W_{r, w, \Delta}$ and $G$ has a unique spline interpolant $s_{G} \in \operatorname{Sp}(r, \Delta)$. The function $F:=G-s_{G}$ has the desired properties (6) and, of course, $F \in W_{r, w, \Delta}$. If $F_{1} \in W_{r, w, \Delta}$ has also the properties (6), then $F-F_{1} \in \mathrm{Sp}(r, \Delta)$ interpolates the zero function and is therefore itself identically zero. Hence $F$ is unique.
(b) Assume there exists a number $z \in[0,1]$ such that

$$
\left|f(z)-s_{f}(z)\right|>|F(z)| .
$$

We set $\Phi:=F(z) /\left(f(z)-s_{f}(z)\right)$ and consider the function $H:=F-$ $\Phi\left(f-s_{f}\right)$ which obviously has the following properties. $H \in W_{r, \Delta}$ because $F, f, s_{f} \in W_{r, \Delta}$,

$$
\begin{equation*}
(-1)^{j} H^{(r)}(x)>0 \text { a.e. in }\left(t_{j}, t_{j+1}\right), \quad 0 \leqslant j \leqslant n, \tag{10}
\end{equation*}
$$

because $|\Phi|<1$ and $|w(x)|>0$ a.e. on $[0,1]$,
$H$ interpolates the zero function and, additionally, $H(z)=0$.
Hence $H$ has at least $m_{0}+1$ distinct zeros in [0, 1]. By Rolle's theorem, the first derivative $H^{\prime}$ has at least $m_{0}$ distinct zeros in $(0,1) \backslash\left\{x_{1} ; \ldots ; x_{k}\right\}$ and at least $m_{0}+m_{1}$ distinct zeros in $[0,1]$. By the same argument we prove that the second derivative $H^{\prime \prime}$ has at least $m_{0}+m_{1}+m_{2}-1$ distinct zeros in [0,1] and, by induction, that $H^{(r-2)}$ has at least $\sum_{q=0}^{r-2} m_{q}-(r-3)=n+3$ distinct zeros in $[0,1]$.

However, since (10) holds and $H^{(r-2)} \in C[0,1]$, it is easy to verify that $H^{(r-2)}$ can have at most $n+2$ distinct zeros in [0, 1]. This contradiction
proves the inequalities (7). (8) is an immediate consequence of (7). The proof for (9) is the same as for (7).

## 4. On $n$-Widths and Interpolation by Splines with Equidistant Knots

As our first application of Theorem 2 we consider the following special case of the interpolation problem (1): Let $n \geqslant 0, r \geqslant 2, \Delta^{*}$ be the collection of equidistant knots $t_{j}=j /(n+1)$, i.e.,

$$
\begin{equation*}
\Delta^{*}: 0=t_{0}<\cdots<t_{j}=\frac{j}{n+1}<\cdots<t_{n+1}=1 . \tag{12}
\end{equation*}
$$

We say that $g \in C^{r-2}[0,1]$ interpolates $f \in C^{r-2}[0,1]$ if

$$
\begin{equation*}
g\left(t_{j}\right)=f\left(t_{j}\right) \quad \text { for } \quad 0 \leqslant j \leqslant n+1, \quad g^{(2 q)}\left(t_{j}\right)=f^{(2 q)}\left(t_{j}\right) \tag{13a}
\end{equation*}
$$

for $j=0$ and $j=n+1,1 \leqslant q \leqslant(r-2) / 2$, provided that $r$ is even, and

$$
\begin{equation*}
g\left(\frac{2 j+1}{2 n+2}\right)=f\left(\frac{2 j+1}{2 n+2}\right) \quad \text { for } 0 \leqslant j \leqslant n, \quad g^{(2 q-1)}\left(t_{j}\right)=f^{(2 q-1)}\left(t_{j}\right) \tag{13b}
\end{equation*}
$$

for $j=0$ and $j=n+1,1 \leqslant q \leqslant(r-1) / 2$, provided that $r$ is odd.
Obviously, the interpolation problem (13) satisfies the assumptions (3)-(5) of Theorem 2 which therefore can be applied to each weight function $w \in L^{1}[0,1]$ with $|w(x)|>0$ a.e. on $[0,1]$. In this section we want to analyse the weight function $w \equiv 1$, for which we are able to present the extremal function $F$ of Theorem 2 explicitly as follows. Let $E_{r}$ be the Euler polynomial of degree $r$ defined by the relation

$$
\begin{equation*}
E_{r}(x)+E_{r}(x+1)=2 x^{r} / r! \tag{14}
\end{equation*}
$$

It is known that

$$
\begin{equation*}
\left\|E_{r}\right\|=K_{r} \pi^{-r}, \quad K_{r}=\frac{4}{\pi} \sum_{k=0}^{\infty} \frac{(-1)^{k(r+1)}}{(2 k+1)^{r+1}} \tag{15}
\end{equation*}
$$

where $\|\cdot\|=\|\cdot\|_{c[0,1]}$ denotes the supremum norm in $[0,1]$. Moreover,

$$
\begin{equation*}
E_{r}^{(2 \theta)}(0)=E_{r}^{(20)}(1)=0 \quad \text { for } \quad 0 \leqslant q \leqslant(r-2) / 2 \tag{16a}
\end{equation*}
$$

provided that $r$ is even, and

$$
\begin{equation*}
E_{r}\left(\frac{1}{2}\right)=0, \quad E_{r}^{(2 q-1)}(0)=E_{r}^{(2 q-1)}(1)=0 \quad \text { for } \quad 1 \leqslant q \leqslant(r-1) / 2 \tag{16b}
\end{equation*}
$$

provided that $r$ is odd.
Additionally, $E_{r}$ is with respect to the line $x=1 / 2$ an even or an odd function if $r$ is even or odd, respectively. Hence the perfect Euler spline $F$ defined by

$$
\begin{equation*}
F(x)=(-1)^{j}(n+1)^{-r} E_{r}((n+1) x-j) \quad \text { for } \quad x \in\left[\frac{j}{n+1}, \frac{j+1}{n+1}\right] \tag{17}
\end{equation*}
$$

$0 \leqslant j \leqslant n$, has the following properties. $F \in W_{r} \subset W_{r, 1, \Delta^{*}}, F$ interpolates the zero function in the sense of (13), and

$$
\begin{equation*}
F^{(r)}(x)=(-1)^{j} \quad \text { for } \quad x \in\left(\frac{j}{n+1}, \frac{j+1}{n+1}\right), \quad 0 \leqslant j \leqslant n \tag{18}
\end{equation*}
$$

In other words, the perfect Euler spline $F$ is the extremal function of Theorem 2 for the interpolation problem (13) and the weight function $w \equiv 1$. Hence we have proved

Theorem 3. Let $\Delta^{*}$ be the collection (12) of equidistant knots. For each function $f \in W_{r}$ there exists a unique spline interpolant $s_{f} \in \operatorname{Sp}\left(r, \Delta^{*}\right)$ which interpolates $f$ in the sense of (13). Moreover,

$$
\begin{equation*}
\left|f(x)-s_{f}(x)\right| \leqslant(n+1)^{-r} E_{r}((n+1) x-j) \quad \text { for } \quad x \in\left[\frac{j}{n+1}, \frac{j+1}{n+1}\right] \tag{19}
\end{equation*}
$$

$0 \leqslant j \leqslant n$, and

$$
\begin{equation*}
\sup \left\{\left\|f-s_{f}\right\|: f \in W_{r}\right\}=(n+1)^{-r}\left\|E_{r}\right\|=(n+1)^{-r} K_{r} \pi^{-r} . \tag{20}
\end{equation*}
$$

To illustrate the extremely good approximation properties of interpolating polynomial splines with equidistant knots we have to introduce the concept of the $n$-widths.

Definition 4. If $W \subset C[0,1]$, then the $n$-width of $W$ in $C[0,1]$ is defined to be

$$
\begin{equation*}
d_{n}(W)=\inf _{X_{n}} \sup _{f \in W} \inf _{g \in X_{n}}\|f-g\| \tag{21}
\end{equation*}
$$

where the infimum is taken over all $n$-dimensional linear subspaces $X_{n}$ of $C[0,1]$.

If, for instance, $W_{r}^{*}$ is the restriction of the class of functions
$\left\{f \mid f^{(r-1)}\right.$ is absolutely continuous on the real line,
$\qquad f$ has the period $1,\left|f^{(r)}(x)\right| \leqslant 1$ a.e. $\}$
to the interval $[0,1]$, it is well known (see Tihomirov [10]) that

$$
\begin{equation*}
d_{2 n-1}\left(W_{r}^{*}\right)=d_{2 n}\left(W_{r}^{*}\right)=K_{r} \pi^{-r}(2 n)^{-r} \tag{22}
\end{equation*}
$$

Since $W_{r}^{*} \subset W_{r}$, it follows from (22) that

$$
\begin{equation*}
d_{n}\left(W_{r}\right) \geqslant d_{n}\left(W_{r}^{*}\right) \geqslant K_{r} \pi^{-r}(n+1)^{-r} \tag{23}
\end{equation*}
$$

and from (20) and (23) that

$$
\begin{equation*}
\sup \left\{\left\|f-s_{f}\right\|: f \in W_{r}\right\} \leqslant d_{n}\left(W_{r}\right) \tag{24}
\end{equation*}
$$

Since $\operatorname{dim} \operatorname{Sp}\left(r, \Delta^{*}\right)=n+r$ we should also look at $d_{n+r}$. From (20) and (23) we obtain

$$
\begin{equation*}
d_{n+r}\left(W_{r}\right) \leqslant \sup \left\{\left\|f-s_{f}\right\|: f \in W_{r}\right\} \leqslant\left(\frac{n+r+1}{n+1}\right)^{r} d_{n+r}\left(W_{r}\right) \tag{25}
\end{equation*}
$$

and

$$
\begin{equation*}
d_{n}\left(W_{r}\right)=K_{r} \pi^{-r}(n+1)^{-r}\left(1+O\left(n^{-1}\right)\right) \quad \text { as } \quad n \rightarrow \infty \tag{26}
\end{equation*}
$$

Thus we have shown that the interpolation (13) by splines of degree $r-1$ with equidistant knots leads to asymptotically best possible error bounds in the sense of $n$-widths.

Remark 2. It has been shown by Tihomirov [10] (see also Chui and Smith [1], Micchelli and Pinkus [7, 8]) that there exists a unique collection $\Delta_{n r}$ of $n-r$ knots in $(0,1)$,

$$
\Delta_{n r}: 0=t_{0}<t_{1}<\cdots<t_{n-r}<t_{n+1-r}=1, \quad n>r
$$

(depending on $n$ and $r$ and not equidistant) such that the spline subspace $\operatorname{Sp}\left(r, \Delta_{n r}\right)$ of dimension $n$ is an extremal subspace for the class $W_{r}$ in the sense of $n$-widths. Again, interpolation at certain $n$ points achieves the desired order of magnitude $d_{n}\left(W_{r}\right)$ of the error. (See Micchelli and Pinkus [7, 8] for more details and more general results.)

Comparing (20) and (26) we conclude that interpolation by splines with equidistant knots is easier to handle than by the extremal spline subspace $\operatorname{Sp}\left(r, \Delta_{n r}\right)$, but the errors are essentially the same, at least for the class $W_{r}$.

Remark 3. Inequality (20) in Theorem 3 is related to results of C. A. Micchelli and A. Pinkus [7; page 169, Example 4] where for the case $r$ even it is done in greater generality. Inequality (20) has also been established by Hall and Meyer [3] for even $r$. Hall and Meyer do not mention the connection to $n$-widths, but for cubic splines they also establish excellent bounds for the derivatives error which I want to analyze here using $n$-widths.

Theorem 4 (Hall and Meyer [3, Theorem 5]). Let $\Delta$ be an arbitrary collection (2) of knots. Let $s_{f} \in \operatorname{Sp}(4, \Delta)$ be the cubic spline interpolant of $f \in C^{4}[0,1]$ with respect to the interpolation problem (13a) or the interpolation problem

$$
\begin{equation*}
s\left(t_{j}\right)=f\left(t_{j}\right) \text { for } 0 \leqslant j \leqslant n+1, \quad s^{\prime}(0)=f^{\prime}(0), \quad s^{\prime}(1)=f^{\prime}(1) \tag{27}
\end{equation*}
$$

Then,

$$
\begin{equation*}
\left\|f^{(q)}-s_{f}^{(q)}\right\| \leqslant C_{q}\left\|f^{(q)}\right\| h^{4-q} \quad \text { for } \quad q=0,1,2,3 \tag{28}
\end{equation*}
$$

where $C_{0}=5 / 384, C_{1}=1 / 24, C_{2}=3 / 8, C_{3}=\left(\eta+\eta^{-1}\right) / 2$ and

$$
\begin{equation*}
h=\max _{0 \leqslant j \leqslant n} h_{j}, \quad h_{j}=t_{j+1}-t_{j}, \quad \eta=h / \min _{0 \leqslant j \leqslant n} h_{j} \tag{29}
\end{equation*}
$$

The constants $C_{0}$ and $C_{1}$ are optimal in the sense that

$$
C_{q}=\sup \left\{\frac{\left\|f^{(q)}-s_{f}^{(q)}\right\|}{\left\|f^{(4)}\right\| h^{4-q}}: f \in C^{4}[0,1], f^{(4)} \not \equiv 0, \Delta \text { arbitrary }\right\}
$$

for $q=0, q=1$.
An easy calculation shows that

$$
\begin{equation*}
C_{0}=\left\|E_{4}\right\|=K_{4} \pi^{-4}, \quad C_{1}=\left\|E_{3}\right\|=K_{3} \pi^{-3}, \quad C_{2}=3\left\|E_{2}\right\|=3 K_{2} \pi^{-2} \tag{30}
\end{equation*}
$$

Therefore, in the equidistant case $h=1 /(n+1)$ the constant $C_{0}$ in (28) is the same as in (20), and the inequalities (28) for $q=1$ and (23) for $r=3$ lead to the surprising result that

$$
\begin{equation*}
d_{n+3}\left(C_{1}^{3}[0,1]\right) \leqslant \sup \left\{\left\|f^{\prime}-s_{f}^{\prime}\right\|: f \in C_{1}^{4}[0,1]\right\} \leqslant d_{n}\left(C_{1}^{3}[0,1]\right) \tag{31}
\end{equation*}
$$

where $C_{1} r[0,1]:=\left\{f \in C^{r}[0,1]:\left\|f^{(r)}\right\| \leqslant 1\right\}$, and we have applied that $C_{1}{ }^{r}[0,1]$ is dense in $W_{r}$ and hence

$$
d_{n}\left(C_{1}^{r}[0,1]\right)=d_{n}\left(W_{r}\right), \quad C_{1}^{3}[0,1] \equiv\left\{f^{\prime} \mid f \in C_{1}^{4}[0,1]\right\}
$$

$s_{f}^{\prime} \in \operatorname{Sp}(3, \Delta)$, and $\operatorname{dim} \operatorname{Sp}(3, \Delta)=n+3$.

Consequently, interpolation by cubic splines with equidistant knots in the sense of (13a) or (27) is up to a negligible factor best possible in the sense of $n$-widths not only for the functions itself but also for their first derivatives. It is as far as I know an open problem if the same holds for higher derivatives and for splines of higher degree.

## 5. Local Upper Bounds in Cubic Spline Interpolation

In this section we discuss a second special case where we also can construct the extremal function $F$ of Theorem 2 explicitly. We discuss the following interpolation problem: For $r=4, n \geqslant 0$, and an arbitrary collection (2) of knots $\Delta: 0=t_{0}<t_{1}<\cdots<t_{n+1}=1$ let $s_{f} \in \operatorname{Sp}(4, \Delta)$ be the unique cubic spline interpolant of $f \in C^{2}[0,1]$ such that

$$
s_{f}\left(t_{j}\right)=f\left(t_{j}\right) \quad \text { for } 0 \leqslant j \leqslant n+1, \quad s_{f}^{\prime \prime}(0)=f^{\prime \prime}(0), \quad s_{f}^{\prime \prime}(1)=f^{\prime \prime}(1)
$$

It is easy to verify that the function

$$
\begin{equation*}
F(x)=(-1)^{j} h_{j} h^{3} E_{4}\left(\frac{x-t_{j}}{h_{j}}\right) \text { for } x \in\left[t_{j}, t_{j+1}\right], \quad 0 \leqslant j \leqslant n \tag{33}
\end{equation*}
$$

is the extremal function of Theorem 2 for the interpolation problem (32) and the weight function $w$,

$$
\begin{equation*}
w(x)=\left(h / h_{j}\right)^{3} \quad \text { for } \quad x \in\left(t_{j}, t_{j+1}\right), \quad 0 \leqslant j \leqslant n \tag{34}
\end{equation*}
$$

where $E_{4}$ is the Euler polynomial of degree 4 and $h$ and $h_{j}$ are defined in (29). Hence, by Theorem 2, we have proved

Theorem 5. For any function $f \in W_{4, w, \Delta}$,

$$
\begin{aligned}
W_{4 . w, \Delta}=\left\{f \in C^{2}[0,1] \mid\right. & f^{(3)} \text { is absolutely continuous in each }\left(t_{j}, t_{j+1}\right) \\
& \text { and } \left.\left|f^{(4)}(x)\right| \leqslant\left(h / h_{j}\right)^{3} \text { a.e. in }\left(t_{j}, t_{j+1}\right), 0 \leqslant j \leqslant n\right\},
\end{aligned}
$$

the unique cubic spline interpolant $s_{f}$ of (32) satisfies the following inequalities:

$$
\begin{gather*}
\left|f(x)-s_{f}(x)\right| \leqslant h_{j} h^{3} E_{4}\left(\frac{x-t_{j}}{h_{j}}\right), \quad x \in\left[t_{j}, t_{j+1}\right], \quad 0 \leqslant j \leqslant n  \tag{35}\\
\left\|f-s_{f}\right\| \leqslant K_{4} \pi^{-4} h^{4}  \tag{36}\\
\left|f^{\prime}\left(t_{j}\right)-s_{f}^{\prime}\left(t_{j}\right)\right| \leqslant K_{3} \pi^{-3} h^{3}, \quad 0 \leqslant j \leqslant n+1 \tag{37}
\end{gather*}
$$

If we compare Theorem 5 with the results of Hall and Meyer in Theorem 4, we realize that we could not establish error bounds for the derivatives; however we obtained the inequality (28) for $q=0$ (remember (30)) even for the larger class of functions $W_{4, w, \Delta}$. Furthermore, inequality (35) yields best possible local error bounds which seem to be new.

Remark 4. The results and the proofs of Theorems 2,3, and 5 can easily be extended to the interpolation of periodic functions by periodic splines.

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